

Perception Logic in Intelligent Systems

Extended Abstract

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Intelligent systems for many real life problems can be modeled by systems of complex objects and their parts changing and interacting over time. The objects are usually linked by certain dependencies, can cooperate between themselves and are able to perform complex and flexible actions (operations) in an autonomous manner. Such systems are identified as complex dynamical systems [1,31], autonomous multiagent systems [18,31], or swarm intelligent systems (see, e.g., [23,5]).

One of the main challenges to be solved in intelligent systems research is the development of methods for approximate reasoning from measurements to perception, i.e., from concepts that can be directly approximated using sensor measurements to concepts, expressed by human beings in natural language, that are the perception results.

The existing methodologies and technologies are not adequate to solve many problems associated with this challenge. Among such problems are, e.g., classification and understanding of medical images [24], control of autonomous systems such as unmanned aerial vehicles or robots (see, e.g., [38,35]) or problems pertaining to monitoring or rescue tasks in multiagent systems [9].

Nowadays, new emerging computing paradigms are investigated in an attempt to develop methods for solving such problems. The further progress depends on a successful cooperation of specialists from different scientific disciplines such as mathematics, logic, philosophy, computer science, artificial intelligence, biology, physics, chemistry, bioinformatics, medicine, neuroscience, linguistics, psychology, and sociology. In particular, different aspects of reasoning from measurements to perception are investigated in psychology [2,14], neuroscience [24], layered learning [29], mathematics of learning [24], machine learning, pattern recognition [12], data mining [15] and also by researchers work-

ing on recently emerged computing paradigms, like computing with words and perception [34], granular computing [20], rough sets, rough mereology, and rough-neural computing [20].

In this lecture we overview some of these new computing paradigms and some of the interactions between various disciplines that have been mentioned.

The concept approximation problem is the basic problem investigated in machine learning, pattern recognition [12] and data mining [15]. It is necessary to induce approximations of concepts (models of concepts) from available experimental data. The data models developed so far in such areas as statistical learning, machine learning, pattern recognition are not satisfactory for approximation of complex concepts that occur in the perception process. Researchers from the different areas have recognized the necessity to work on new methods for concept approximation (see, e.g., [6,32]). The main reason for this is that these complex concepts are, in a sense, too far from measurements which makes the searching for relevant features infeasible in a very huge space. There are several research directions aiming at overcoming this difficulty. One of them is based on the interdisciplinary research where the knowledge pertaining to perception in psychology or neuroscience is used to help to deal with complex concepts (see, e.g., [24]). There is a great effort in neuroscience towards understanding the hierarchical structures of neural networks in living organisms [10,24]. Also mathematicians are recognizing problems of learning as the main problem of the current century [24]. These problems are closely related to complex system modeling as well. In such systems again the problem of concept approximation and its role in reasoning about perceptions is one of the challenges nowadays. One should take into account that modeling complex phenomena entails the use of local models (captured by local agents, if one would like to use the multi-agent terminology [18]) that should

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be fused afterwards. This process involves negotiations between agents [18] to resolve contradictions and conflicts in local modeling. This kind of modeling is becoming more and more important in dealing with complex real-life phenomena which we are unable to model using traditional analytical approaches. The latter approaches lead to exact models. However, the necessary assumptions used to develop them result in solutions that are too far from reality to be accepted. New methods or even a new science therefore should be developed for such modeling [13].

One of the possible approaches in developing methods for complex concept approximations can be based on the layered learning [29]. Inducing concept approximation should be developed hierarchically starting from concepts that can be directly approximated using sensor measurements toward complex target concepts related to perception. This general idea can be realized using additional domain knowledge represented in natural language. For example, one can use some rules of behavior on the roads, expressed in natural language, to assess from recordings (made, e.g., by camera and other sensors) of actual traffic situations, if a particular situation is safe or not [19]. To deal with such problems one should develop methods for concept approximations together with methods aiming at approximation of reasoning schemes (over such concepts) expressed in natural language. The foundations of such an approach, creating a core of perception logic, are based on rough set theory [22] and its extension rough mereology [25,20], both invented in Poland, in combination with other soft computing tools, in particular with fuzzy sets.

Rough set theory due to Zdzisaw Pawlak [22], is a mathematical approach to imperfect knowledge. The problem of imperfect knowledge has been tackled for a long time by philosophers, logicians and mathematicians. Recently it became also a crucial issue for computer scientists, particularly in the area of artificial intelligence. There are many approaches to the problem of how to understand and manipulate imperfect knowledge. The most successful one is, no doubt, the fuzzy set theory proposed by Lotfi A. Zadeh [33]. Rough set theory presents still another attempt to solve this problem. It is based on an assumption that objects are perceived by partial information about them. Due to this some objects can be indiscernible. From this fact it follows that some sets can not be exactly described by available information about objects; they are rough not crisp. Any rough set is

characterized by its (lower and upper) approximations. The difference between the upper and lower approximation of a given set is called its boundary. Rough set theory expresses vagueness by employing a boundary region of a set. If the boundary region of a set is empty it means that the set is crisp, otherwise the set is rough (inexact). A nonempty boundary region of a set indicates that our knowledge about the set is not sufficient to define the set precisely. One can recognize that rough set theory is, in a sense, a formalization of the idea presented by Gotlob Frege [11].

One of the very successful techniques for rough set methods was Boolean reasoning [7]. The idea of Boolean reasoning is based on construction for a given problem P a corresponding Boolean function f_P with the following property: the solutions for the problem P can be decoded from prime implicants of the Boolean function f_P . It is worth to mention that to solve real-life problems it is necessary to deal with Boolean functions having a large number of variables.

A successful methodology based on the discernibility of objects and Boolean reasoning has been developed in rough set theory for computing of many key constructs like reducts and their approximations, decision rules, association rules, discretization of real value attributes, symbolic value grouping, searching for new features defined by oblique hyperplanes or higher order surfaces, pattern extraction from data as well as conflict resolution or negotiation [26]. Most of the problems involving the computation of these entities are NP-complete or NP-hard. However, we have been successful in developing efficient heuristics yielding sub-optimal solutions for these problems. The results of experiments on many data sets are very promising. They show very good quality of solutions generated by the heuristics in comparison with other methods reported in literature (e.g., with respect to the classification quality of unseen objects). Moreover, they are very time-efficient. It is important to note that the methodology makes it possible to construct heuristics having a very important approximation property. Namely, expressions generated by heuristics (i.e., implicants) close to prime implicants define approximate solutions for the problem (see, e.g., [37]).

A question arises if the methods developed so far based on Boolean and approximate Boolean reasoning can be scaled to the case of complex problems considered here.

Rough set theory has attracted attention of many researchers and practitioners all over the

world, who have contributed essentially to its development and applications. The rough set approach seems to be of fundamental importance to AI and cognitive sciences, especially in the areas of machine learning, knowledge acquisition, decision analysis, knowledge discovery from databases, expert systems, inductive reasoning and pattern recognition.

One of the consequences of perceiving objects using only available information about them is that for some objects one cannot decide if they belong to a given set or not. However, one can estimate the degree to which objects belong to sets. This is another crucial observation in building foundations for approximate reasoning. In dealing with imperfect knowledge one can only characterize satisfiability of relations between objects to a degree, not precisely. Among relations on objects the rough inclusion relation, which describes to what degree objects are parts of other objects, plays a special role. A rough mereological approach (see, e.g., [25,28,20]) is an extension of the Leśniewski mereology [17] and is based on the relation *to be a part to a degree*. It will be interesting to note here that Jan Lukasiewicz was the first who started to investigate the inclusion to a degree of concepts in his discussion one relationships between probability and logical calculi [16].

In a more general setting, objects we are dealing with are information granules. Such granules are obtained as the result of information granulation (see, e.g., [34,27,28,20]). Information granulation can be viewed as a human way of achieving data compression and it plays a key role in implementation of the strategy of divide-and-conquer in human problem-solving [34].

Computing with Words and Perceptions “derives from the fact that it opens the door to computation and reasoning with information which is perception - rather than measurement-based. Perceptions play a key role in human cognition, and underlie the remarkable human capability to perform a wide variety of physical and mental tasks without any measurements and any computations. Everyday examples of such tasks are driving a car in city traffic, playing tennis and summarizing a story” [34].

The rough mereological approach (see, e.g., [25, 20]) is based on calculi of information granules for constructing complex concept approximations. Constructions of information granules should be robust with respect to their input information granule deviations. Hence, the information granule construction process itself can also be granulated. As the result the so called AR schemes (AR networks)

[25–28] are obtained. AR schemes can be interpreted as complex patterns [15]. Searching methods for such patterns relevant for a given target concept have been developed [28]. Methods for deriving relevant AR schemes are computationally expensive. This complexity can be substantially reduced by using domain knowledge. In such a case AR schemes are derived in conformity with reasoning schemes in natural language that are elicited from domain knowledge. Developing methods for deriving such AR schemes is one of the main goals of our current projects.

Let us mention some examples.

The prediction of behavioral patterns of a complex object evaluated over time is usually based on some historical knowledge representation used to store information about changes in relevant features or parameters. This information is usually represented as a data set and has to be collected during long-term observation of a complex dynamic system. For example, in case of road traffic, we associate the object-vehicle parameters with the readouts of different measuring devices or technical equipment placed inside the vehicle or in the outside environment (e.g., alongside the road, in a helicopter observing the situation on the road, in a traffic patrol vehicle). Many monitoring devices serve as informative sensors such as GPS, laser scanners, thermometers, range finders, digital cameras, radar, image and sound converters (see, e.g. [31]). Hence, many vehicle features serve as models of physical sensors. Here are some exemplary sensors: location, speed, current acceleration or deceleration, visibility, humidity (slipperiness) of the road. By analogy to this example, many features of complex objects are often dubbed sensors. In the lecture we discuss (see also [4]) some rough set tools for perception modelling that make it possible to recognize behavioral patterns of objects and their parts changing over time. More complex behaviour of complex objects or groups of complex objects can be presented in the form of *behavioral graphs*. Any behavioral graph can be interpreted as a *behavioral pattern* and can be used as a complex classifier for recognition of complex behaviours. We outline [4] the complete approach to the perception of behavioral patterns, that is based on behavioral graphs and the dynamic elimination of behavioral patterns. The tools for dynamic elimination of behavioral patterns are used for switching-off in the *system attention* procedures searching for identification of some behavioral patterns. The developed rough set tools for perception modeling are used to model networks of classifiers.

Such networks make it possible to recognize behavioral patterns of objects changing over time. They are constructed using an ontology of concepts provided by experts that engage in approximate reasoning on concepts embedded in such an ontology. Experiments on data from a vehicular traffic simulator [36] are showing that the developed methods are useful in the identification of behavioral patterns.

Our second example concerns human computer-interfaces that allow for a dialog with experts to transfer their knowledge to the system about structurally complex objects to the system. For pattern recognition systems [8], e.g., for Optical Character Recognition (OCR) systems it will be helpful to transfer to the system a certain knowledge about the expert view on border line cases. The central issue in such pattern recognition systems is the construction of classifiers within vast and poorly understood search spaces, which is a very difficult task. Nonetheless, this process can be greatly enhanced with knowledge about the investigated objects provided by an human expert. We outline a framework for the transfer of such knowledge from the expert and it is shown how to incorporate it into the learning process of a recognition system using methods based on rough mereology [30]. It is also demonstrated how this knowledge acquisition can be conducted in an interactive manner, with a large dataset of handwritten digits as an example.

The outlined research directions create, in our projects, foundations toward understanding the nature of reasoning from measurements to perception. Understanding such reasoning processes is fundamental for developing intelligent systems based on perception logic.

A further understanding of perception logic in interdisciplinary projects will make it possible to use discoveries from the different scientific disciplines mentioned in this article for improving the performance of intelligent systems.

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